

## In the Claims

---

1           1.     (currently amended) An apparatus for communication to a network  
2     and ~~for use with~~ including at least a first and second object, each of which  
3     objects is characterized by a location, comprising:

4           a location circuit installed in each object which detects location information  
5     of the corresponding object in real-time;

6           a processor with memory installed in each object coupled to the location  
7     circuit, which processor receives the location information and activates  
8     responsive functions according to the corresponding object's current location and  
9     which processor stores events of the corresponding object in a history file; and

10          a communication circuit installed in each object coupled to the processor  
11     in the same object to transmit ~~messages to the network~~ and to receive messages  
12     ~~from within~~ the network,

13          where the processor corresponding to the first object automatically  
14     activates selected functions controlling the first object in response to the location  
15     of the second object.

1           2.     (currently amended) The apparatus of claim 1 in further  
2     combination with at least one but not more than three satellites of a global  
3     positioning system and where the location circuit comprises a GPS receiver

4 communicating with the at least one satellite of the global positioning system and  
5 communicating with a terrestrial location detection network to determine the  
6 position of the object from a combination of signals from the global positioning  
7 system and terrestrial location detection network.

1 3. (cancelled)

1 4. (cancelled).

A2  
con rd

1 5. (currently amended) The apparatus of claim 1 in further  
2 combination with a single satellite of a global positioning system and where the  
3 location circuit comprises a GPS receiver communicating with the satellite of the  
4 global positioning system and a terrestrial location detection network in  
5 combination ~~The apparatus of claim 4~~ where the processor in each object  
6 controls the location circuit in the same object to first determine location of the  
7 corresponding object using the GPS receiver and then uses the terrestrial  
8 location detection network to determine location only if the GPS receiver fails to  
9 provide valid locational information.

1 6. (original) The apparatus of claim 1 where the events of the history  
2 file stored by the processor in each object includes location, time of day, speed,  
3 and direction of the corresponding object for each event.

1           7.       (original) The apparatus of claim 6 where the events of the history  
2 file stored by the processor in each object include the type of the event.

1           8.       (original) The apparatus of claim 7 where the events of the history  
2 file stored by the processor in each object include sent and received messages.

1           9.       (original) The apparatus of claim 1 in further combination with a  
2 remote server communicated through the network with one of the first and  
3 second objects where an event of the history file stored by the processor in each  
4 object is sent to the remote server and then cleared by the processor in the  
5 corresponding object from the memory in the corresponding object.

1           10.      (currently amended) The apparatus of claim 9, wherein at least  
2 one of the objects is mobile, and where location information, information relating  
3 to an event, requests submitted from an object to the remote server or to other  
4 objects, and the related actions recorded in the mobile object are ~~is~~ cleared by  
5 the processor in each object from the memory in the corresponding object on a  
6 periodic basis.

1           11.      (currently amended) The apparatus of claim 9, wherein at least one  
2 of the objects is mobile, and where location information, information relating to an  
3 event, requests submitted from an object to the remote server or to other objects,

4 and the related actions recorded in the mobile object are is-cleared by the  
5 processor in each object from the memory in the corresponding object at the time  
6 that event of the history file stored by the processor in each object is sent to the  
7 remote server.

1 12. (cancelled)

1 13. (original) The apparatus of claim 1 where the communication  
2 circuit in each object comprises a plurality of wireless modems, a satellite modem  
3 and a frequency adjustable transceiver in each object coupled to the wireless  
4 modems and satellite modem in the corresponding object, wherein the processor  
5 in each object is coupled to and controls the frequency adjustable transceiver in  
6 the corresponding object to select a best signal from the wireless modems in the  
7 corresponding object, but if the best signal from the wireless modems in the  
8 corresponding object fails to satisfy a predetermined threshold, then the  
9 processor in each object controls the frequency adjustable transceiver in the  
10 corresponding object to select a signal from the satellite modem in the  
11 corresponding object.

1 14. (currently) The apparatus of claim 1 where the communication  
2 circuit comprises a two-way radio for communicating with each of the objects and  
3 wherein at least one object has locational information which is shared with the  
4 other objects, and where the processor in each object stores all valid location

5 fixes and where the location circuit in the corresponding object comprises in the  
6 corresponding object a GPS engine board, a receiver for communication to the  
7 network coupled to the GPS engine board, and a position computation circuit  
8 coupled to the receiver, the GPS engine board, receiver and position  
9 computation circuit being coupled to the processor, where the processor in each  
10 object controls the GPS engine board in the corresponding object to determine  
11 location of the corresponding object, but if the GPS engine board in the  
12 corresponding object fails to provide a valid location fix, the processor in the  
13 corresponding object then controls the position computation circuit in the  
14 corresponding object to provide a location by dead reckoning based on the last  
15 recorded valid location fix including that obtained from another object.

A2  
contd

1 15. (original) The apparatus of claim 14 where the position  
2 computation circuit in the each object comprises a gyro and a speed sensor to  
3 provide dead reckoning input data from which the processor in the corresponding  
4 object calculates a dead reckoning location.

1 16. (cancelled)

1 17. (currently amended) The apparatus of claim 1 further comprising a  
2 plurality of input/output ports in the corresponding object coupled to the  
3 processor in each object and a plurality of external devices in the corresponding  
4 object coupled to the plurality of input/output ports in the object.

1 18. (currently amended) A method comprising:  
2 detecting location information of a plurality of objects in real-time in a  
3 corresponding location circuit in each object;  
4 inputting the location information into a processor in each object with  
5 memory in the corresponding object coupled to the location circuit in the  
6 corresponding object;  
7 storing events of each object in a history file in the memory in the  
8 corresponding object; and  
9 transmitting messages from each of the objects ~~to a network~~; and  
10 activating a responsive function in at least one of the objects through the  
11 network according to the corresponding object's location, where the processor  
12 corresponding to the at least one object automatically activates a selected  
13 function to control the same object in response to the location of the other one of  
14 the objects.

1 19. (currently amended) The method of claim 18 in further combination  
2 with at least one, but not more than three satellites of a global positioning system  
3 and where detecting location information of at least one object in real-time  
4 comprises communicating a GPS receiver in the corresponding object with at  
5 least one satellite of the global positioning system.

1           20.   (original) The method of claim 18 where detecting location  
2 information of at least one object in real-time comprises communicating the  
3 corresponding object with a terrestrial location detection network.

4           21.   (cancelled)

1           22.   (currently amended) The method of claim 18 in further combination  
2 with a single satellite of a global positioning system and where detecting location  
3 information of at least one object in real-time comprises communicating a GPS  
4 receiver in the corresponding object with the satellite of the global positioning  
5 system and a terrestrial location detection network in combination. ~~The method~~  
6 ~~of claim 21~~ where communicating a GPS receiver in the corresponding object  
7 with at least one satellite of the global positioning system and a terrestrial  
8 location detection network in combination comprises controlling the location  
9 circuit in the corresponding object to first determine location using the GPS  
10 receiver in the corresponding object and then communicating the corresponding  
11 object with the terrestrial location detection network to determine location only if  
12 the GPS receiver in the corresponding object fails to provide valid locational  
13 information.

1           23.   (original) The method of claim 18 where storing events of the  
2 corresponding object in a history file comprises storing location, time of day,

3 speed, and direction of the corresponding object for each event relating to the  
4 corresponding object.

1 24. (original) The method of claim 23 where storing events of the  
2 corresponding object in a history file comprises storing the type of the event  
3 relating to the corresponding object.

1 25. (original) The method of claim 24 where storing events of the  
2 corresponding object in a history file comprises storing sent and received  
3 messages relating to the corresponding object in the corresponding object.

Handwritten initials "A2" and "con" with a checkmark.

1 26. (original) The method of claim 18 further comprising  
2 communicating with a remote server through the network with one objects where  
3 an event of the history file stored by the processor in the corresponding object is  
4 sent to the remote server and then cleared by the processor in the corresponding  
5 object from memory in the corresponding object.

1 27. (original) The method of claim 26 where clearing the event of the  
2 history file in the corresponding object is performed on a periodic basis.

3 28. (original) The method of claim 26 where clearing the event of the  
4 history file in the corresponding object is performed at the time that event of the



5 history file stored by the processor in the corresponding object is sent to the  
6 remote server.

1 29. (original) The method of claim 18 where at least one of the objects  
2 is moving.

1 30. (cancelled)

A2  
can be  
1 31. (original) The method of claim 18 where transmitting messages  
2 from each of the objects to a network comprises in each of the corresponding  
3 objects transmitting through a plurality of wireless modems, a satellite modem  
4 and a frequency adjustable transceiver in each of the corresponding objects  
5 coupled to the wireless modems and satellite modem in the corresponding  
6 objects, wherein the processor in each of the corresponding objects is coupled to  
7 and controls the frequency adjustable transceiver in the corresponding object to  
8 select a best signal from the wireless modems in the corresponding object, but if  
9 the best signal from the wireless modems in the corresponding object fails to  
10 satisfy a predetermined threshold, then the processor in the corresponding object  
11 controls the frequency adjustable transceiver in the corresponding object to  
12 select a signal from the satellite modem in the corresponding object.

32. (currently amended) The method of claim 18 further comprising  
communicating with each of the objects by means of a two-way radio, where at  
least one of the objects has locational information stored therein which is  
communicated to another object, and storing all valid location fixes in the  
corresponding object and where detecting location information in the  
corresponding object comprises operating in each object a GPS engine board, a  
receiver for communication to the network coupled to the GPS engine board, and  
a position computation circuit to the receiver in the corresponding object, the  
GPS engine board, receiver and position computation circuit being coupled in  
each object to the processor in the corresponding object, the processor in each  
object controlling the GPS engine board in the corresponding object to determine  
location of the corresponding object, but if the GPS engine board in the  
corresponding object fails to provide a valid location fix, the processor in the  
corresponding object then controlling the position computation circuit in the  
corresponding object to provide a location by dead reckoning based on the last  
recorded valid location fix including that obtained from another object.

33. (original) The method of claim 32 where providing a location by  
dead reckoning in the corresponding object comprises using a gyro and a speed  
sensor in the corresponding object to provide dead reckoning input data and  
calculating a dead reckoning location using the processor in the corresponding  
object.

1            34.    (cancelled)

1            35.    (original) The method of claim 18 further comprising  
2 communicating in each object through a plurality of input/output ports between  
3 the processor and a plurality of external devices coupled the plurality of  
4 input/output ports in the corresponding object.

1            36.    (cancelled)

1            37.    (currently amended) An apparatus for use with an object  
2 characterized by a location in combination with a single satellite of a global  
3 positioning system and a terrestrial location detection network, comprising:  
4 a location circuit which detects location information of the object in real-  
5 time including a GPS receiver communicating with the satellite of the global  
6 positioning system and the terrestrial location detection network;  
7 a processor with memory coupled to the location circuit, which processor  
8 receives the location information and activates responsive functions according to  
9 the object's current location; and  
10 a communications circuit coupled to the location circuit. ~~The apparatus of~~  
11 ~~claim 36~~ where the processor controls the location circuit to first determine  
12 location using the GPS receiver and then uses the terrestrial location detection  
13 network to determine location only if the GPS receiver fails to provide valid  
14 locational information.

1            38.    (original) The apparatus of claim 37 ~~36~~ where the communication  
2 circuit comprises a plurality of wireless modems, a satellite modem and a  
3 frequency adjustable transceiver coupled to the wireless modems and satellite  
4 modem, wherein the processor is coupled to and controls the frequency  
5 adjustable transceiver to select a best signal from the wireless modems, but if the  
6 best signal from the wireless modems fails to satisfy a predetermined threshold,  
7 then the processor controls the frequency adjustable transceiver to select a  
8 signal from the satellite modem.

Ar  
amended

1            39.    (currently amended) The apparatus of claim 37 ~~36~~ where the  
2 communication circuit comprises a two-way radio for communicating with each of  
3 the objects, where at least of the objects has locational information stored therein  
4 and where the processor stores all valid location fixes and where the location  
5 circuit comprises a GPS engine board, a receiver for communication to the  
6 network coupled to the GPS engine board, and a position computation circuit  
7 coupled to the receiver, the GPS engine board, receiver and position  
8 computation circuit being coupled to the processor, where the processor controls  
9 the GPS engine board to determine location of the corresponding object, but if  
10 the GPS engine board fails to provide a valid location fix, the processor then  
11 controls the position computation circuit to provide a location by dead reckoning  
12 based on the last recorded valid location fix including that obtained from another  
13 object.

1           40.   (original) The apparatus of claim 39 where the position  
2 computation circuit comprises a gyro and a speed sensor to provide dead  
3 reckoning input data from which the processor calculates a dead reckoning  
4 location.

1           41.   (cancelled)

1           42.   (cancelled)

1           43.   (currently amended) A method used in combination with a single  
2 satellite of a global positioning system and at least one terrestrially based  
3 positioning system comprising:  
4           detecting location information of at least one object in real-time by  
5 selectively communicating a GPS receiver with the satellite of the global  
6 positioning system or by selectively communicating a terrestrial receiver with at  
7 least one terrestrially based positioning system; and  
8           inputting the location information into a processor with memory in the  
9 object. ~~The method of claim 42 where communicating a GPS receiver with at~~  
10 least one satellite of the global positioning system and a terrestrial location  
11 detection network in combination comprises controlling a location circuit to first  
12 determine location using the GPS receiver and then communicating with the  
13 terrestrial location detection network to determine location only if the GPS  
14 receiver fails to provide valid locational information.

1           44.   (original) The method of claim 42 further comprising transmitting  
2 through a plurality of wireless modems, a satellite modem and a frequency  
3 adjustable transceiver coupled to the wireless modems and satellite modem,  
4 wherein the processor is coupled to and controls the frequency adjustable  
5 transceiver to select a best signal from the wireless modems, but if the best  
6 signal from the wireless modems fails to satisfy a predetermined threshold, then  
7 the processor controls the frequency adjustable transceiver to select a signal  
8 from the satellite modem.

Handwritten: *can read*

1           45.   (currently amended) The method of claim 42 further comprising  
2 communicating with each of the objects by means of a two-way radio, where at  
3 least one of the objects has locational information stored therein and storing all  
4 valid location fixes and where detecting location information comprises operating  
5 a GPS engine board, a receiver for communication to the network coupled to the  
6 GPS engine board, and a position computation circuit coupled to the receiver, the  
7 GPS engine board, receiver and position computation circuit being coupled to the  
8 processor, the processor controlling the GPS engine board to determine location  
9 of the corresponding object, but if the GPS engine board fails to provide a valid  
10 location fix, the processor then controlling the position computation circuit to  
11 provide a location by dead reckoning based on the last recorded valid location fix  
12 including that from another object.

1           46.   (original) The method of claim 45 where providing a location by  
2 dead reckoning comprises using a gyro and a speed sensor to provide dead  
3 reckoning input data and calculating a dead reckoning location using the  
4 processor.

1           47.   (cancelled)

1           48.   (currently amended) An apparatus for communication to a location-  
2 detection network, including a global positioning satellite system, and for use with  
3 an object which is characterized by a location, comprising:

4           a location circuit installed in the object which detects location information  
5 of the object in real-time independently of the extent of GPS coverage by a  
6 plurality of dead reckoning means for determining location based on last known  
7 position as determined by GPS;

8           a processor with memory installed in the object coupled to the location  
9 circuit, which processor receives the location information; and

10          a communication circuit installed in the object and coupled to the  
11 processor to communicate with the location-detection network.

1           49.   (currently amended) The apparatus of claim 48 where the location  
2 circuit comprises a GPS receiver communicating with the at least one but not  
3 more than three satellites of the global positioning satellite system and a  
4 terrestrial location detection network to determine the position of the object from

5 a combination of signals from the global positioning system and terrestrial  
6 location detection network.

1 50. (original) The apparatus of claim 48 where the location-detection  
2 network includes a terrestrially based location detection network and where the  
3 location circuit communicates through the communication circuit with the  
4 terrestrially based location detection network.

A2  
cancel 1 51. - 52. (cancelled)

1 53. (original) The apparatus of claim 48 where the communication  
2 circuit comprises a plurality of wireless modems, a satellite modem and a  
3 frequency adjustable transceiver coupled to the wireless modems and satellite  
4 modem, wherein the processor is coupled to and controls the frequency  
5 adjustable transceiver to select a best signal from the wireless modems, but if the  
6 best signal from the wireless modems fails to satisfy a predetermined threshold,  
7 then the processor controls the frequency adjustable transceiver to select a  
8 signal from the satellite modem.

1 54. (currently amended) The apparatus of claim 48 where the  
2 communication circuit comprises a two-way radio for communicating with each of  
3 the objects where at least one object has locational information stored therein,



4 and where the processor stores all valid location fixes and where the location  
5 circuit comprises a GPS engine board, a receiver for communication to the  
6 network coupled to the GPS engine board, and a position computation circuit  
7 coupled to the receiver, the GPS engine board, receiver and position  
8 computation circuit being coupled to the processor, where the processor controls  
9 the GPS engine board to determine location of the corresponding object, but if  
10 the GPS engine board fails to provide a valid location fix, the processor then  
11 controls the position computation circuit to provide a location by dead reckoning  
12 based on the last recorded valid location fix including that from another object.

A2  
can be

1 55. (original) The apparatus of claim 54 where the position  
2 computation circuit comprises a gyro and a speed sensor to provide dead  
3 reckoning input data from which the processor calculates a dead reckoning  
4 location.

1 56. (cancelled)

1 57. (currently amended) A method for communication to a location-  
2 detection network, including a global positioning satellite system, and for use with  
3 an object, which is characterized by a location, comprising:  
4 selectively communicating with selected portions of the location-detection  
5 network including a global positioning satellite system;

6 detecting location information of an object in real-time independently of the  
7 extent of GPS coverage by a plurality of dead reckoning means for determining  
8 location based on last known position as determined by GPS; and  
9 inputting the location information into a processor with memory.

1 58. (currently amended) The method of claim 57 where selectively  
2 communicating with selected portions of the location-detection network including  
3 a global positioning satellite system comprises communicating a GPS receiver  
4 with at least one, but not more than three satellites of the global positioning  
5 system and a terrestrial location detection network in combination.

A2  
cmd  
1 59. (original) The method of claim 58 where communicating a GPS  
2 receiver with at least one satellite of the global positioning system and a  
3 terrestrial location detection network in combination comprises controlling the  
4 location circuit to first determine location using the GPS receiver and then  
5 communicating with the terrestrial location detection network to determine  
6 location only if the GPS receiver fails to provide valid locational information.

1 60. (original) The method of claim 57 where selectively communicating  
2 with selected portions of the location-detection network including a global  
3 positioning satellite system comprises transmitting through a plurality of wireless  
4 modems, a satellite modem and a frequency adjustable transceiver coupled to  
5 the wireless modems and satellite modem, wherein the processor is coupled to

6 and controls the frequency adjustable transceiver to select a best signal from the  
7 wireless modems, but if the best signal from the wireless modems fails to satisfy  
8 a predetermined threshold, then the processor controls the frequency adjustable  
9 transceiver to select a signal from the satellite modem.

1 61. (currently amended) The method of claim 57 further comprising  
2 communicating with each of the objects by means of a two-way radio where at  
3 least one of the objects has locational information stored therein, and storing all  
4 valid location fixes and where detecting location information comprises operating  
5 a GPS engine board, a receiver for communication to the network coupled to the  
6 GPS engine board, and a position computation circuit coupled to the receiver, the  
7 GPS engine board, receiver and position computation circuit being coupled to the  
8 processor, the processor controlling the GPS engine board to determine location  
9 of the corresponding object, but if the GPS engine board fails to provide a valid  
10 location fix, the processor then controlling the position computation circuit to  
11 provide a location by dead reckoning based on the last recorded valid location fix  
12 including that from another object.

1 62. (original) The method of claim 61 where providing a location by  
2 dead reckoning comprises using a gyro and a speed sensor to provide dead  
3 reckoning input data and calculating a dead reckoning location using the  
4 processor.

A2  
cancel.

63. (cancelled)

---